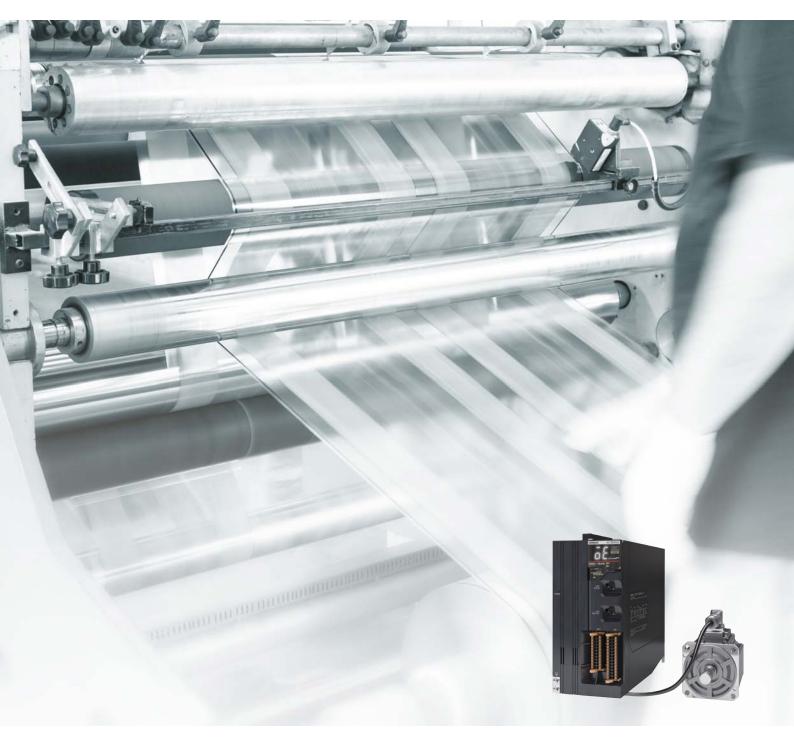


# Higher Productivity and Safer Environment











# Higher productivity and Safer environment





Advanced safety control for "Human", "Machine" and "Product"



Manufacturing and maintenance without machine stopping



Avoiding interference of machine and product by keeping control when unexpected shut down



Zero-loss production thanks to synchronized emergency stop



## Simplifying Motion and Safety

The 1S servo drive with motion safety functionality provides protection for the machine operators from fatal injuries and shorter machine downtimes. Integrating motion safety functions into the servo drive minimize costs, components and wiring complexity. This model supports motion safety but it is even further evolved based on the concept of the standard 1S series. With the highest-level of motion control performance and safety functionality, productivity can be further improved.



Ether CAT.







· The NX-series Safety Network Controller in combination with the NX1 Machine Automation Controller provides real-time safety control of up to 12 motors using EtherCAT and FSoE.

### Servo features

- Power range from 200 W to 3 kW
- · 20 bit high resolution encoder
- · 350% momentary maximum torque (200 V, 750 W max.)
- · Battery-free absolute multi-turn encoder
- · Safety over EtherCAT (FSoE)

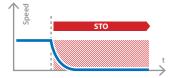




### High adaptability for machine safety

STO SS1 SS2 SOS SLS SLP SDI SBC (PLe SIL3) with FSoE





### Safe Torque Off (STO)

Torque is safely removed from the motor. Motor stops by Inertia (or Dynamic Brake). It is the ultimate safest function. When other safety functions fail the drive executes STO.



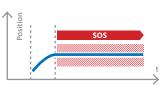
### Safe Stop 1 (SS1)

Timed STO. The torque in the motor is removed at a certain (settable) time after SS1 activation, so the controller has time to stop the load in a controlled manner before the STO is executed.



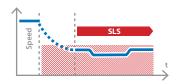
### Safe Stop 2 (SS2)

Timed SOS. SOS is activated after some delay.



### Safe Operating Stop (SOS)

Motor stays standstill in the stop position. Torque in the shaft is allowed.



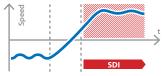
### Safely-Limited Speed (SLS)

Drive monitors that a certain maximum speed is not exceeded.



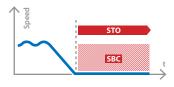
### Safely-Limited Position (SLP)

Drive monitors that actual position is inside "safe" limits.



#### Safe Direction (SDI)

Drive guarantees that the movement occurs only in one direction (rotation).



#### Safe Brake Control (SBC)

Drive can activate and monitor the status of an external Safe Brake. Drive has dedicated IO's for this functionality. This function is usually linked to STO function.

\* Note: motor brake is "holding brake", not safe.



### Quick Installation: One Cable

- $\cdot$  Power, encoder and brake in one pre-assembled cable with IP67 connector
- · Pluggable connectors for easy pre-wiring and system maintenance
- Fast and secure screw-less push-in in all connectors

From



Rotating connector



### Time Reduction: Integrated Programming and Testing

- · Auto definition of I/F variables
- · Motion safety function blocks
- · Graphical GUI
- · Integrated Data Trace



Time Reduction



Integrated Programming Integrated Testing

Motion+Safety Motion+Safety

Programming



### **ISSUE**

• In a machine operation intervention such as removing a crashed product, the machine is stopped, so there is no production.

#### **SOLUTION**

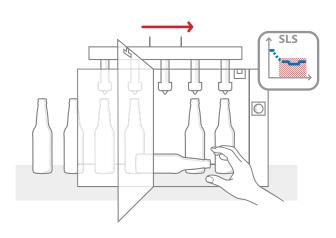
- You can pickup the product safely with Safely-Limited Speed function. The production line is running at limited speed but it is not stopped.
- · Machine restarts smoothly from speed limit to normal speed.

### **ISSUE**

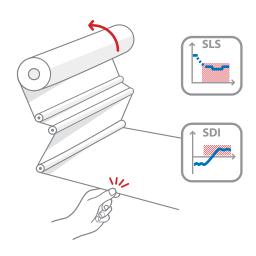
• In a coil change, the machine operator has to set the material in each roll with inching or jog function. It makes the change over complex and time consuming.

#### **SOLUTION**

 Machine operator can set the material in the roll with Safely-Limited Speed and introduce the film smoothly with Safe Direction function. It helps the operator to reduce the change over time and complexity.



Minimize operation intervention time



Reduce changeover time



### **ISSUE**

• In a machine operation intervention, the stacker is stopped, so there is no production.

### **SOLUTION**

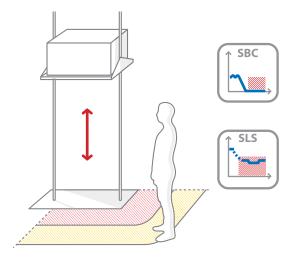
- When the operator is close, the stacker run slowly with Safely-Limited Speed without stopping.
- If the operator gets too close, then the Safe Brake Control function is activated to hold the stacker in a safer mode.

### ISSUE

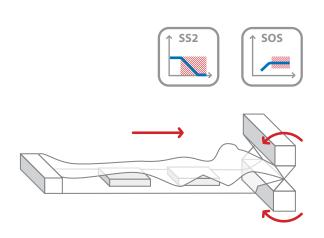
• Disposal of product waste occurs. If the power to a motor is stopped following an emergency stop, film may be caught in the machine.

### **SOLUTION**

- Even in the event of machine stoppage due to an emergency stop, disposal of product waste will not occur.
- Power is continuously supplied to a motor even during the emergency stop, therefore preventing film from getting caught in the machine.

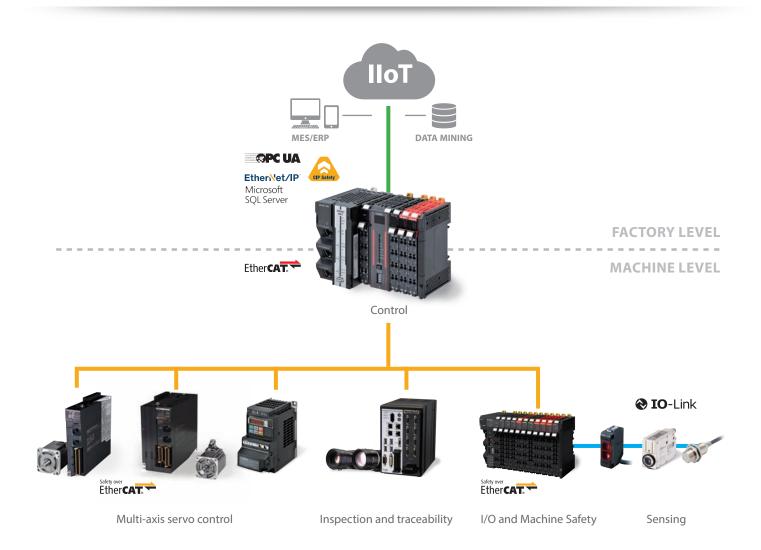


Avoid machine stops



Zero startup rejects

## Sysmac Automation Platform







### Sysmac Studio, the integrated software

- $\boldsymbol{\cdot}$  One single tool for logic sequence, motion, safety, robotics, vision and HMI
- Fully compliant with open standard IEC 61131-3
- · PLCopen Function Blocks for Motion and Safety
- · Supports Ladder, Structured Text and In-Line ST programming with a rich instruction set
- · CAM editor for easy programming of complex motion profiles
- Database Connectivity Function Block library

### Sysmac Library

• The Sysmac Library is a collection of software functional components that can be used in programs for the NJ/NX Machine Automation Controllers. Sample programs and HMI screen samples are also available.

Please download it from following URL and install to Sysmac Studio. http://www.ia.omron.com/sysmac\_library/

## Sysmac servo family

### Machine Controller





The NX-series Safety Network Controller connected with the NX1 Machine Controller enables the use of both EtherNet/IP + CIP Safety and EtherCAT + FSoE at the same time.

### NJ/NX series

- · Logic sequence, Motion, Safety, Robotics and Database connection functionality
- · Scalable motion control: CPUs from 2 up to 256
- IEC 61131-3 controller
- · PLCopen Function Blocks for Motion Control and Safety
- · Advanced motion with Robotics functionality
- Built-in EtherCAT and EtherNet/IP ports

### Motion



### 1S Motion Safety servo

- · Servo drive for rotary motors
- · Up to 3kW
- · Battery-free absolute multi-turn encoder
- Advanced safety functions: STO/SS1/SS2/SOS/SLS/ SLP/SDI/SBC
- · Servo drive for rotary motors with one cable connection

### 1S Servo System - General purpose servo

- · Servo drive for rotary motors
- · Up to 15kW
- · Battery-free absolute multi-turn encoder
- · Safety function: R88D-1SN□-ECT : STO R88D-1SN□-ECT-51: STO/SS1/SLS







### G5 Servo System

- · Servo drive for rotary or linear motors
- Rotary motor: Up to 15 kW
- · Iron-core and Ironless linear motor models: Up to 2100 N peak force
- · Safety function: STO (Hardwired Safe Torque Off only)
- Full closed loop control

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### MEMO

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Note: Do not use this document to operate the Unit.

### **OMRON Corporation** Industrial Automation Company

Kyoto, JAPAN Contact : www.ia.omron.com

### Regional Headquarters

### OMRON EUROPE B.V.

Wegalaan 67-69, 2132 JD Hoofddorp The Netherlands Tel: (31) 2356-81-300 Fax: (31) 2356-81-388

### OMRON ASIA PACIFIC PTE. LTD.

438B Alexandra Road, #08-01/02 Alexandra Technopark, Singapore 119968 Tel: (65) 6835-3011 Fax: (65) 6835-3011

### OMRON ELECTRONICS LLC

2895 Greenspoint Parkway, Suite 200 Hoffman Estates, IL 60169 U.S.A. Tel: (1) 847-843-7900 Fax: (1) 847-843-7787

### OMRON (CHINA) CO., LTD.

Room 2211, Bank of China Tower, 200 Yin Cheng Zhong Road, PuDong New Area, Shanghai, 200120, China Tel: (86) 21-6023-0333 Fax: (86) 21-5037-2388

### Authorized Distributor:

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